



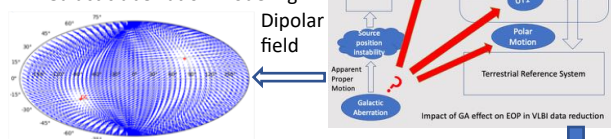
## Introduction

The variation of Earth orientation characterized by Earth orientation parameters (EOPs) is of interest in astronomy and geophysics. EOPs connect the celestial reference frame (CRF) and terrestrial reference frame (TRF) and should be in accordance with realizations of CRF and TRF.

The ICRF3, a new version of CRF, was adopted by the XXX IAU General Assembly. Theoretically, EOP series determined within the frame of the new CRF would differ from the old one from ICRF2. We address the impact on the EOP estimates due to the switch from the ICRF2 to the ICRF3 in the VLBI data reduction.

## From ICRF2 to ICRF3

- Nearly 10 year more data
- Galactic aberration modeling



## VLBI solutions

Table 1: Configuration of VLBI solutions.

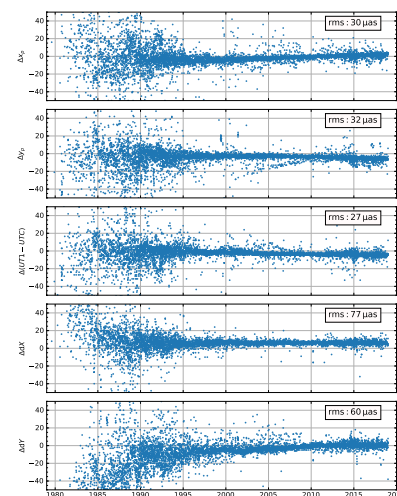
Solution	GA modeling	A priori radio source position
icrf2	No	ICRF2
icrf3	Yes	ICRF3
icrf3_nga	No	ICRF3

Global/Independent;  
Data span 1979.5-2019.0;  
6585 sessions;  
~13.5 million delays

- Generally, for global solution the change from ICRF2 to ICRF3 has tiny influences on polar motion and UT1. On the nutation, there is no significant difference on the MHB nutation terms and FCN. But a linear rate of +0.4  $\mu\text{s}/\text{yr}$  will be introduced in  $dY$  which should be noticed. Such effects are not sensitive to the network geometry.
- For independent solution, attention should be paid to  $dY$  component of nutation in the EOP forecast since the difference increases when it moves far away for the GA reference epoch J2015.0

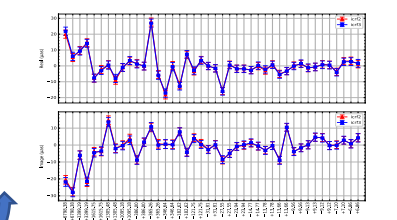
## EOP differences for global solutions (i)

Differences between EOP time series for three solutions. Unit:  $\mu\text{s}$ .



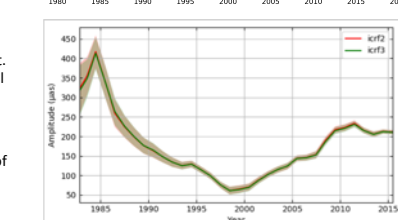
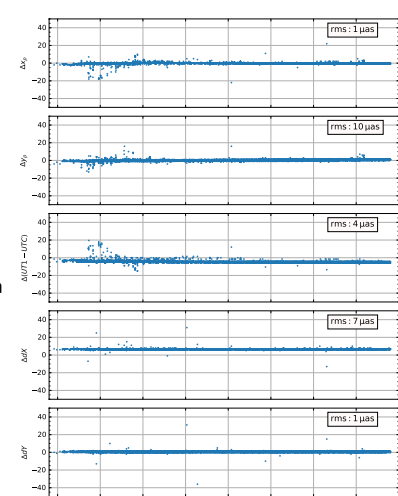
icrf3  
minus  
icrf2

icrf3\_nga  
minus  
icrf2



Nutation  
residual wrt.  
MHB model

Yearly  
amplitude of  
Free core  
nutation



Amplitude (μs)

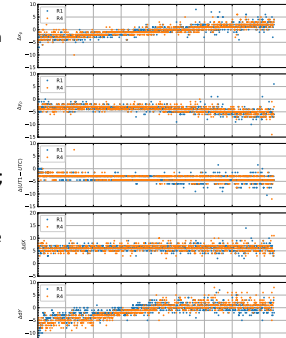
## EOP differences for global solutions (ii)

Table 2: Linear drift from EOP offsets of "icrf3-icrf2" (unit:  $\mu\text{s}/\text{yr}$ ).

	$\Delta x_p$	$\Delta y_p$	$\Delta(UT1 - UTC)$	$\Delta dX$	$\Delta dY$
All	$+0.2 \pm 0.2$	$-0.1 \pm 0.2$	$-0.2 \pm 0.1$	$-0.0 \pm 0.1$	$+0.4 \pm 0.1$
R1	$+0.3 \pm 0.2$	$-0.2 \pm 0.2$	$-0.2 \pm 0.1$	$-0.1 \pm 0.1$	$+0.2 \pm 0.1$
R4	$+0.3 \pm 0.2$	$-0.1 \pm 0.2$	$-0.1 \pm 0.1$	$+0.0 \pm 0.1$	$+0.4 \pm 0.1$

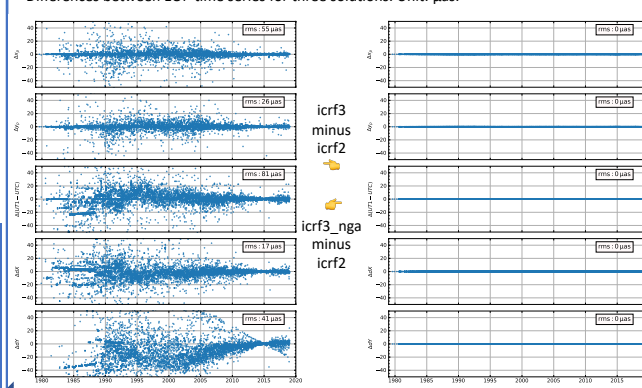
Differences between  
EOP time series for IVS-  
R1/R4 sessions of icrf3  
minus icrf2. Unit:  $\mu\text{s}$ .

- Small scatter  $\leq 10 \mu\text{s}$  after 1995;
- EOP estimate differences coming mainly from the inclusion of the GA modeling;
- RMS  $\sim 30 \mu\text{s}$  in polar motion and UT1 but insignificant wrt. formal errors  $\sim 100 \mu\text{s}$ , nearly half of that for nutation offsets;
- Offset  $\sim 5 \mu\text{s}$  in  $dX$  difference for nutation; Noisier among 2002-2010 but stable within
- 5  $\mu\text{s}$  after 2010 in  $dY$  difference for nutation; Nutation residuals in MHB term shows consistent amplitudes between two solution;
- So does the yearly amplitude of the free core nutation modeled by Lambert (2007);
- EOP differences from IVS R1 and R4 sessions agrees well with each other;
- Linear drift could found in  $dY$ ,  $\sim +0.4 \mu\text{s}/\text{yr}$ ;



## EOP differences for independent solutions

Differences between EOP time series for three solutions. Unit:  $\mu\text{s}$ .



# Conclusion